

Cray XC30 System: Overview

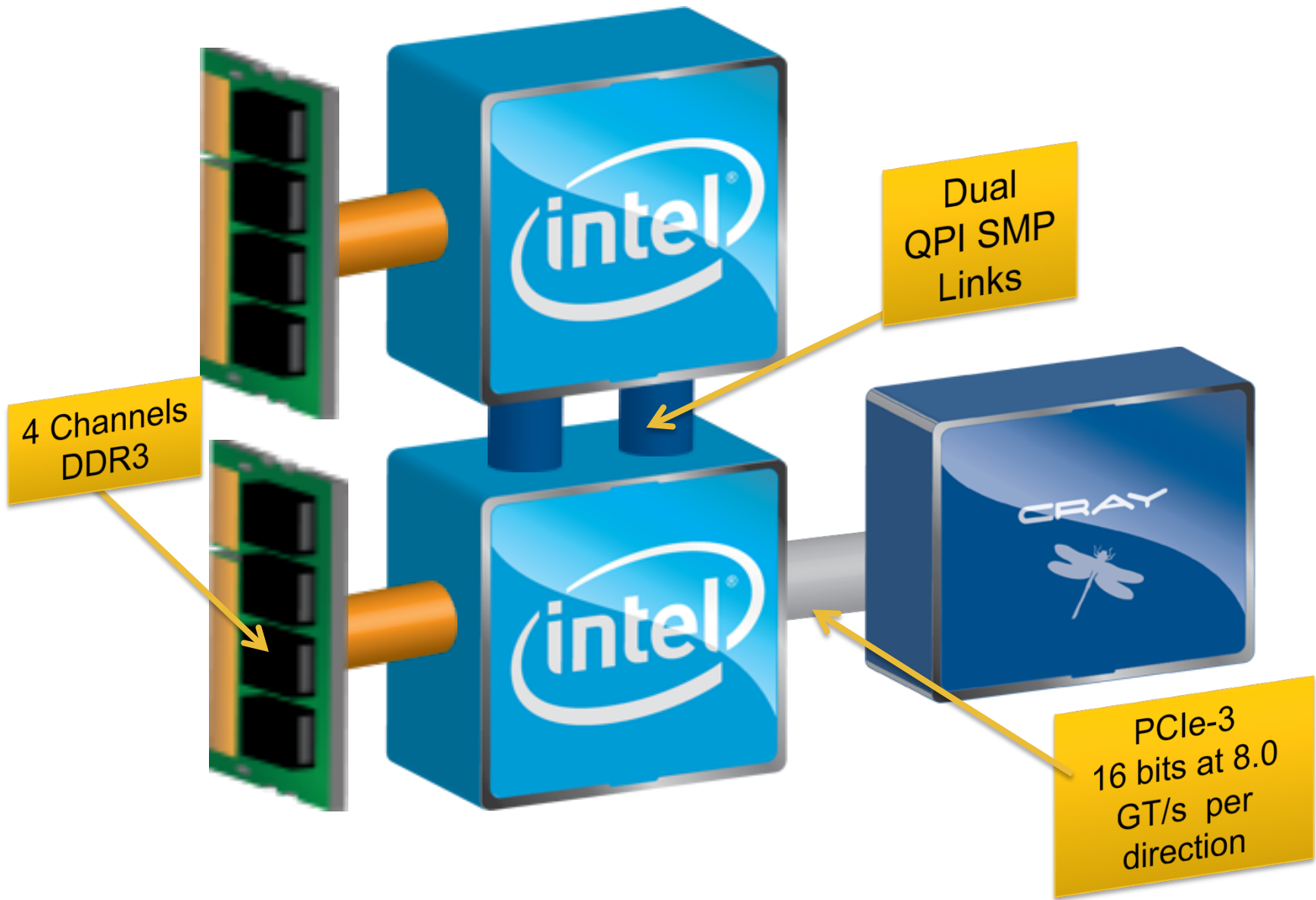
Nathan Wichmann
wichmann@cray.com



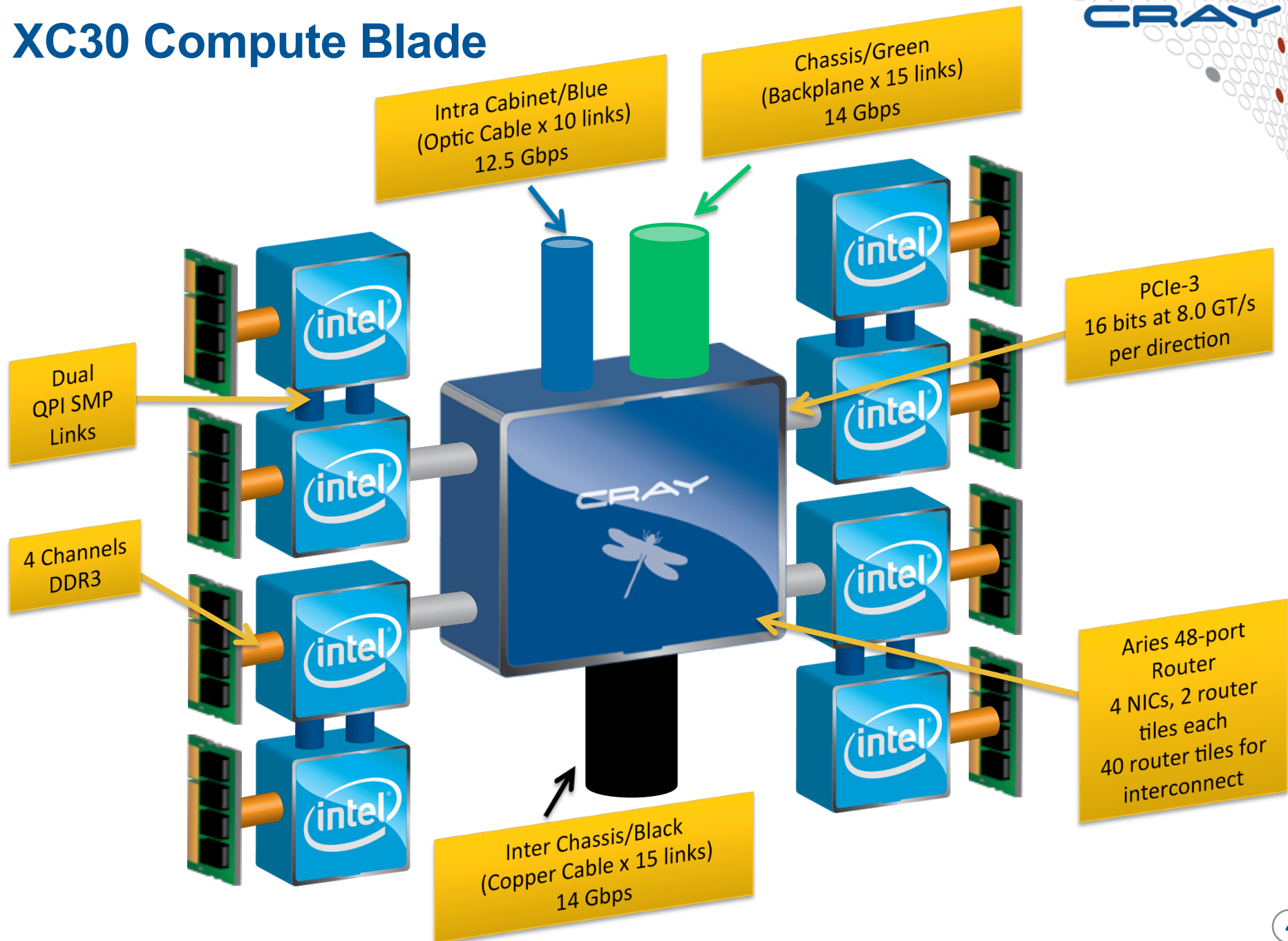
Outline

- **Building Blocks**
- **A new compute node**
- **Dragonfly Topology**
- **Network and benchmark performance**

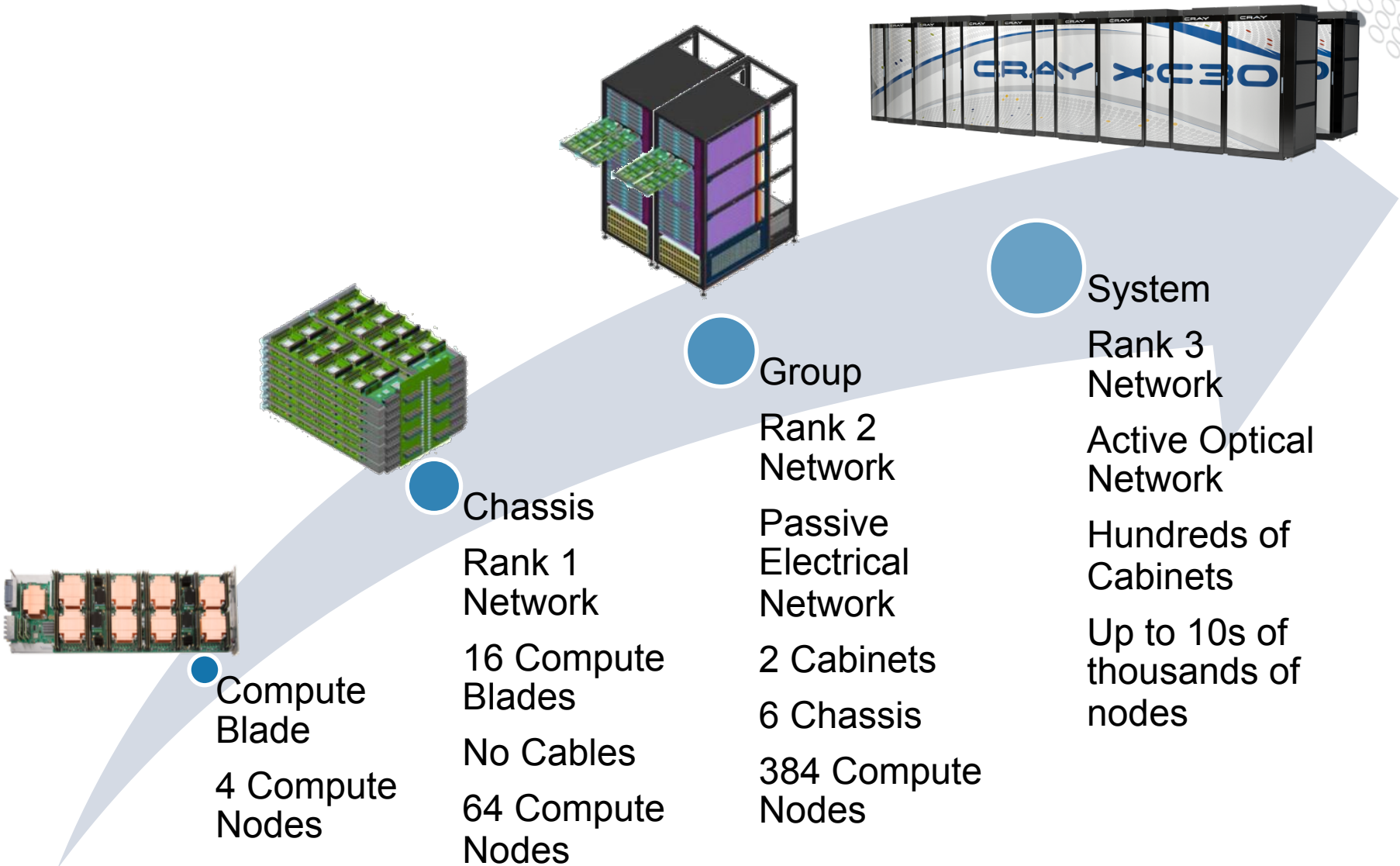
Cray XC30 Compute Blade Architecture



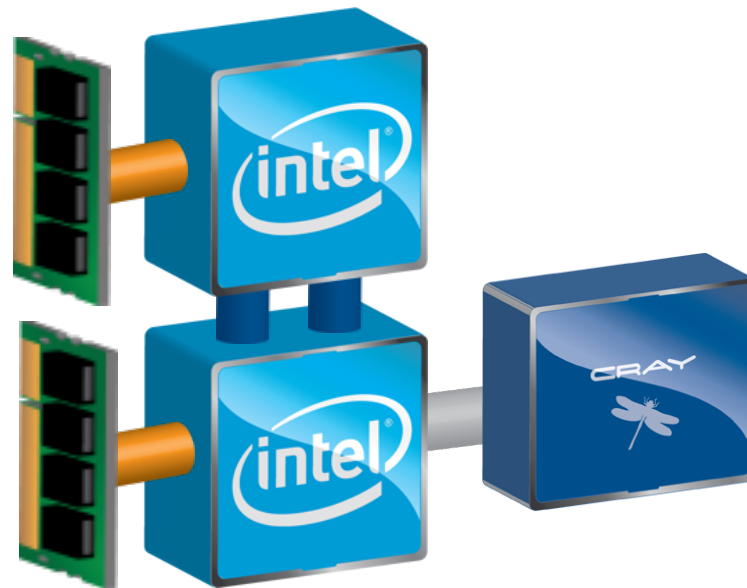
XC30 Compute Blade

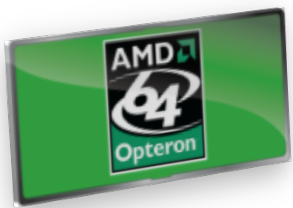


Cray XC30 System Building Blocks

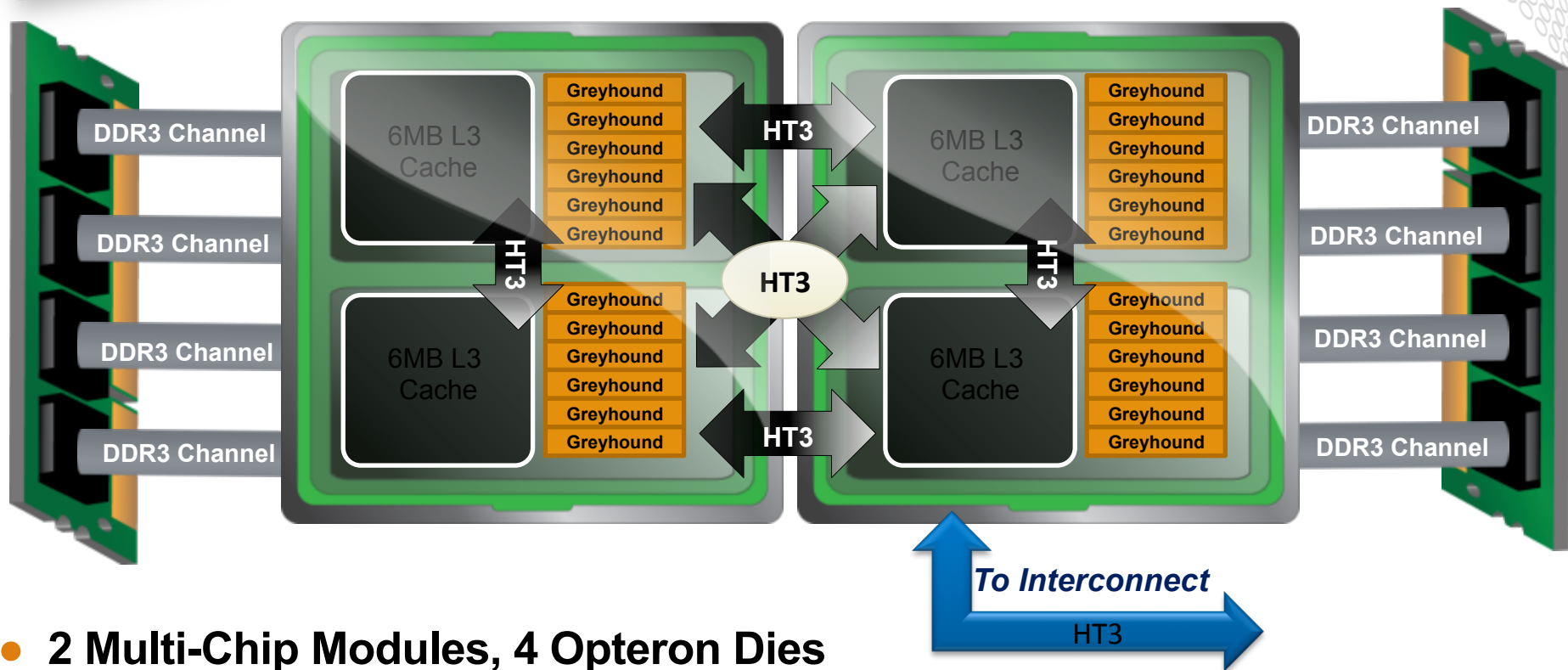


Cray XC30 Compute node: Processor and environment comparison



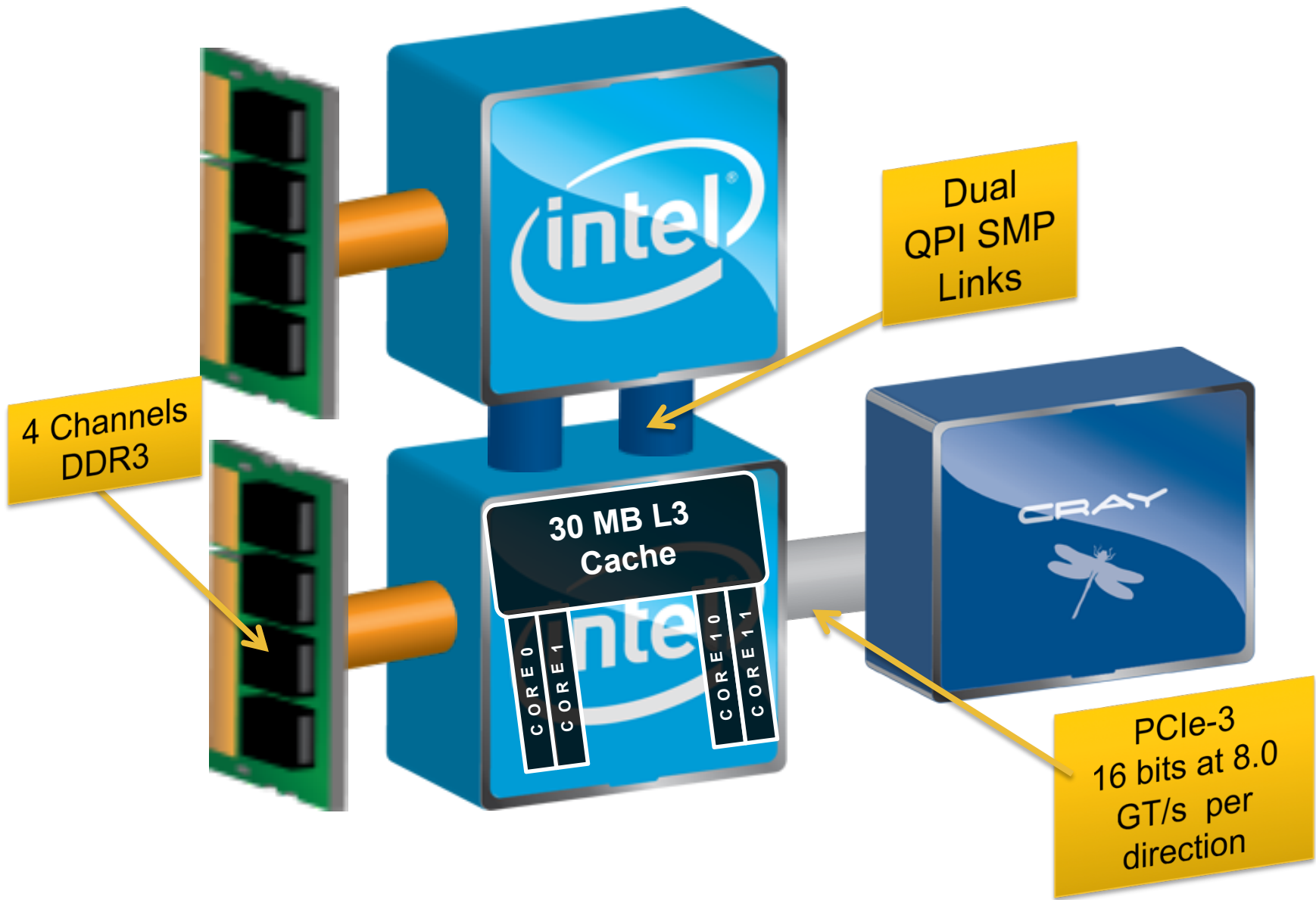


XE6 Compute Node Details: 24-core Magny Cours



- 2 Multi-Chip Modules, 4 Opteron Dies
- 24 (or 16) Computational Cores, 24 MB of L3 cache
- 8 Channels of DDR3 Bandwidth to 8 DIMMs
- Dies are fully connected with HT3

Cray XC30 Compute Blade Architecture





Magny Cours vs Ivybridge: bake-off

MAGNY COURS

- 6 cores per die
 - 4 die per node
- Each core has
 - 1 user thread
 - 1 SSE (vector) functional group
 - 128 bits wide
 - 1 add and 1 multiply
 - L1 cache size = 32 Kbytes
 - L2 cache size = .5 Mbytes
- L3 cache, size = 6 Mbytes
- Cache per core = $.5 + 6/6 = 1.5$ Mbytes
- Cache BW per core
 - L1 / L2 / L3 = 35 / 3.2 / 3.2 Gbytes/s
- Stream TRIAD BW/node = 52 Gbytes/s
- Peak DP FP per core = 4 flops/clock
- Peak DP FP per node = 96 flops/clock
- Memory latency = 110 ns

Ivybridge

- 12 cores per die
 - 2 die per node
- Each core has
 - 1 or 2 user threads
 - 1 AVX (vector) functional group
 - 256 bits wide
 - 1 add and 1 multiply
 - L1 cache size = 32 Kbytes
 - L2 cache size = 256 kbytes
- L3 cache, size = 30 Mbytes
- Cache per core = $30/8 = 2.5$ Mbytes
- Cache BW per core
 - L1 / L2 / L3 = 100 / 40 / 23 Gbytes/s
- Stream TRIAD BW / Node = 100 Gbytes/s
- Peak DP FP per core = 8 flops/clock
- Peak DP FP per node = 480 Gflops
- Memory latency = 82 ns



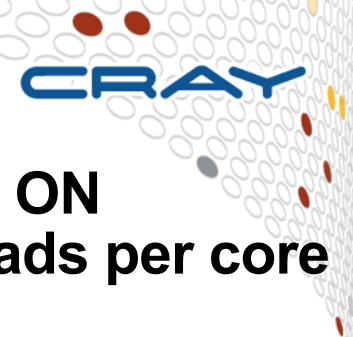
Sandybridge and Ivybridge

Sandybridge

- 8 cores per die
 - 2 die per node
- Each core has
 - 1 or 2 user threads
 - 1 AVX (vector) functional group
 - 256 bits wide
 - 1 add and 1 multiply
 - L1 cache size = 32 Kbytes
 - L2 cache size = 256 kbytes
- L3 cache, size = 20 Mbytes
- Cache per core = $20/8 = 2.5$ Mbytes
- Cache BW per core
 - L1 / L2 / L3 = 105 / 42 / 26 Gbytes/s
- Stream TRIAD BW / Node = 77 Gbytes/s
- Peak DP FP per core = 8 flops/clock
- Peak DP FP per node = 320 Gflops
- Memory latency = 82 ns

Ivybridge

- 12 cores per die
 - 2 die per node
- Each core has
 - 1 or 2 user threads
 - 1 AVX (vector) functional group
 - 256 bits wide
 - 1 add and 1 multiply
 - L1 cache size = 32 Kbytes
 - L2 cache size = 256 kbytes
- L3 cache, size = 30 Mbytes
- Cache per core = $30/8 = 2.5$ Mbytes
- Cache BW per core
 - L1 / L2 / L3 = 100 / 40 / 23 Gbytes/s
- Stream TRIAD BW / Node = 100 Gbytes/s
- Peak DP FP per core = 8 flops/clock
- Peak DP FP per node = 480 Gflops
- Memory latency = 82 ns



Single Stream vs Dual Stream

- Cray compute nodes booted with hyperthreads always ON
- User can choose to run with one or two ranks/pes/threads per core
- Choice made at runtime
- `aprun -n#### -j1 ...` -> Single Stream mode, one rank per core
- `aprun -n#### -j2 ...` -> Dual Stream mode, two ranks per core
- Default is Single Stream
- Dual Stream often better if...
 - throughput is more important OR...
 - performance per node is more important OR...
 - your code scales extremely well
- Single Stream often better if...
 - single job performance matters more
 - per core performance matters most (code does not scale well)
- Cray ended up running 4 or the 7 “NERSC SSP” codes in dual stream mode to maximize overall system score



Core specialization

- System 'noise' on compute nodes may significantly degrade scalability for some applications
- Core Specialization can mitigate this problem
 - M core(s)/cpu(s) per node will be dedicated for system work (service core)
 - As many system interrupts as possible will be forced to execute on the service core
 - The application will not run on the service cpus
- Use **aprun -r** to get core specialization
 - \$ aprun -r[1-8] -n 100 a.out**
- Highest numbered cpus will be used
 - Starts with cpu 31 on Sandybridge nodes
- Independent of aprun -j setting
- **apcount** provided to compute total number of cores required
 - man apcount**



Running with OpenMP and the Intel PE

- An extra thread created by the Intel OpenMP runtime interacts with the CLE thread binding mechanism and causes poor performance
- To work around this issue **cpu-binding should be turned off**
 - Allows user compute threads to spread out over available resources
 - Helper thread will no longer impact performance
- Note: This is only an issue for running OpenMP programs that were compiled and linked with the Intel compiler



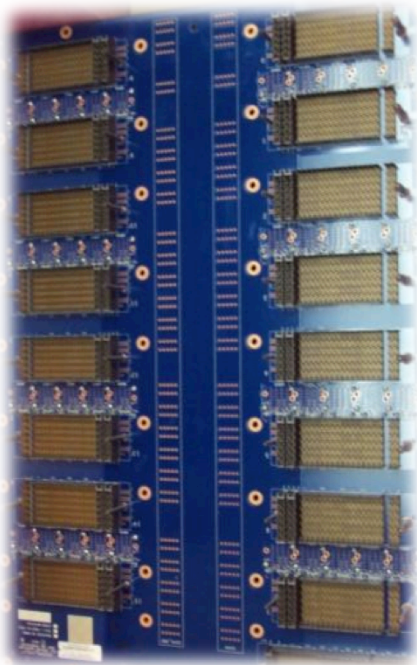
- **Running when “depth” divides evenly into the number of “cpus” on a socket**
export OMP_NUM_THREADS=“<=depth”
aprun -n npes -d “depth” -cc numa_node a.out
- **Running when “depth” does not divide evenly into the number of “cpus” on a socket**
export OMP_NUM_THREADS=“<=depth”
aprun -n npes -d “depth” -cc none a.out
- **Take into account –j1 vs –j2**
- **These “-cc” options turn off cpu binding**
 - Your process/thread may switch cores in the middle of execution
- **Would LOVE to see a comparison of performance between shutting off binding and forcing binding**

Cray XC30 Dragonfly Topology



Cray XC30 Network

- The Cray XC30 system is built around the idea of optimizing interconnect bandwidth and associated cost at every level



Rank-1
PC Board: ¢¢¢

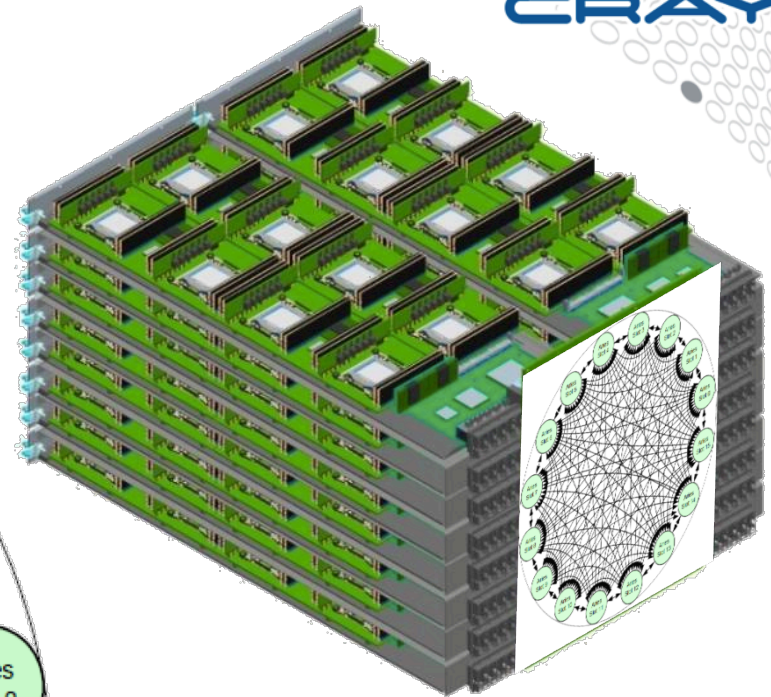
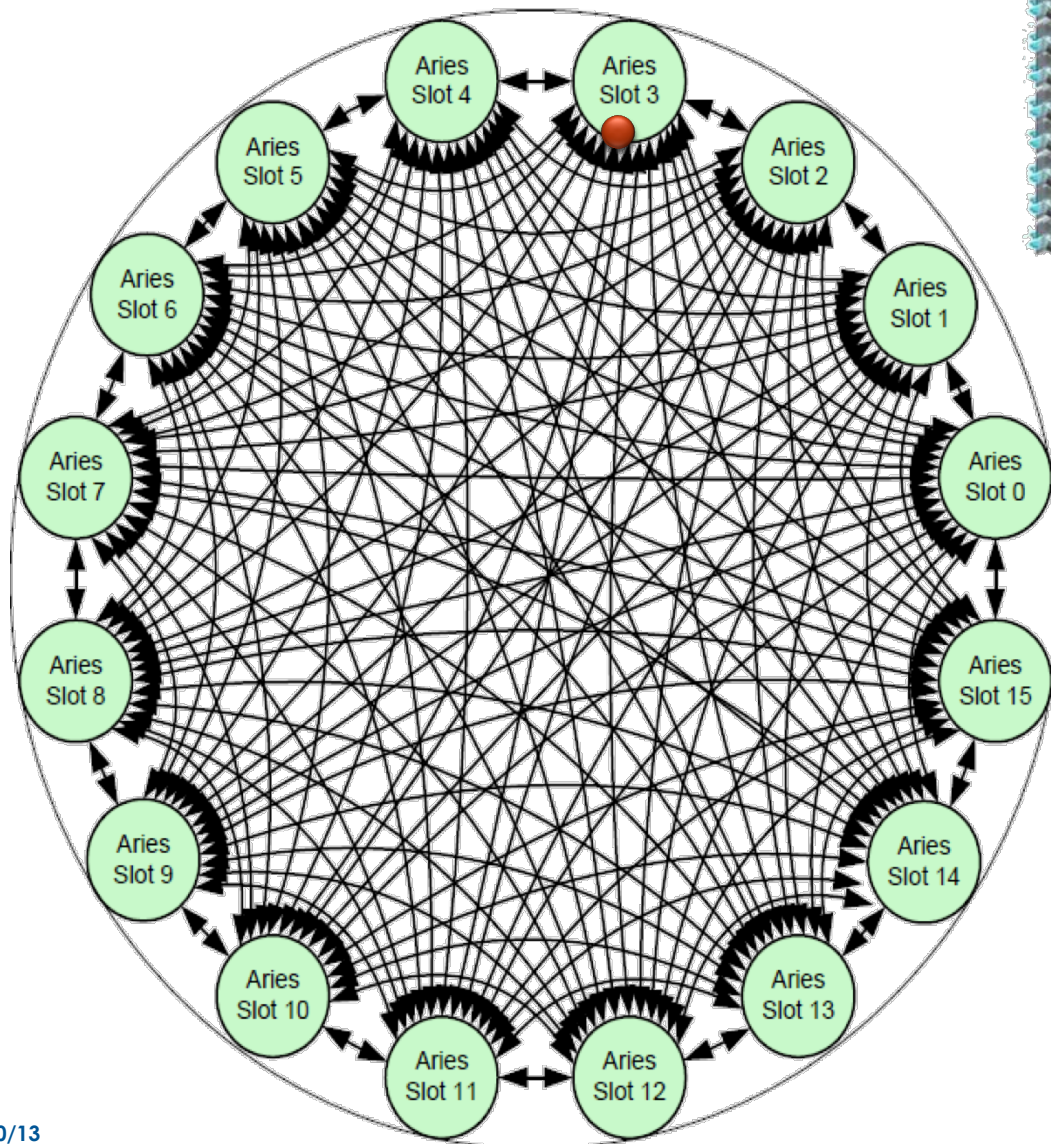


Rank-2
Passive CU: \$



Rank-3
Active Optics: \$\$\$

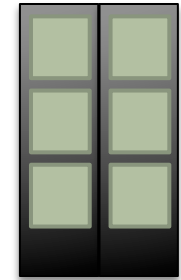
Cray XC30 Rank1 Network



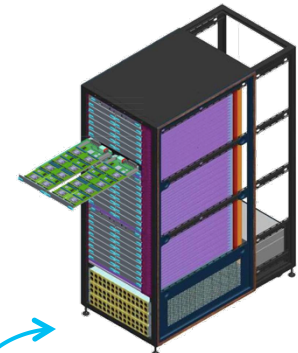
- Chassis with 16 compute blades
- 128 Sockets
- Inter-Aries communication over backplane
- Per-Packet adaptive Routing

Cascade – Local Electrical Network

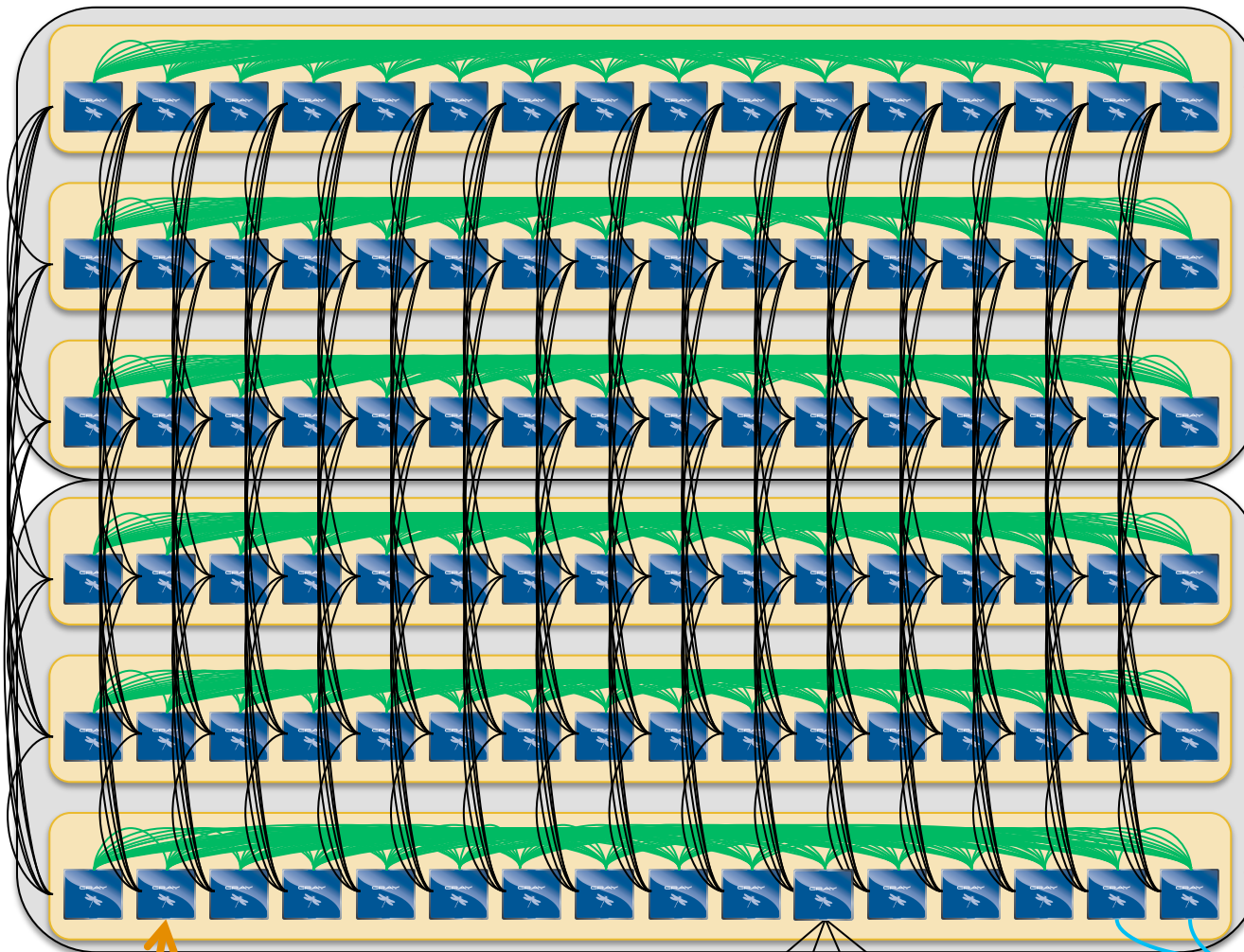
**2 Cabinet
Group
768 Sockets**



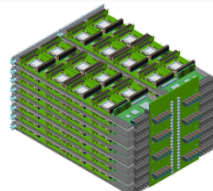
**6 backplanes
connected with
copper cables in a 2-
cabinet group:
“Rank-2 Network”**



**Active optical
cables interconnect
groups
“Rank-3 Network”**



**16 Aries connected
by backplane
“Green Network”**



**4 nodes
connect to a
single Aries**

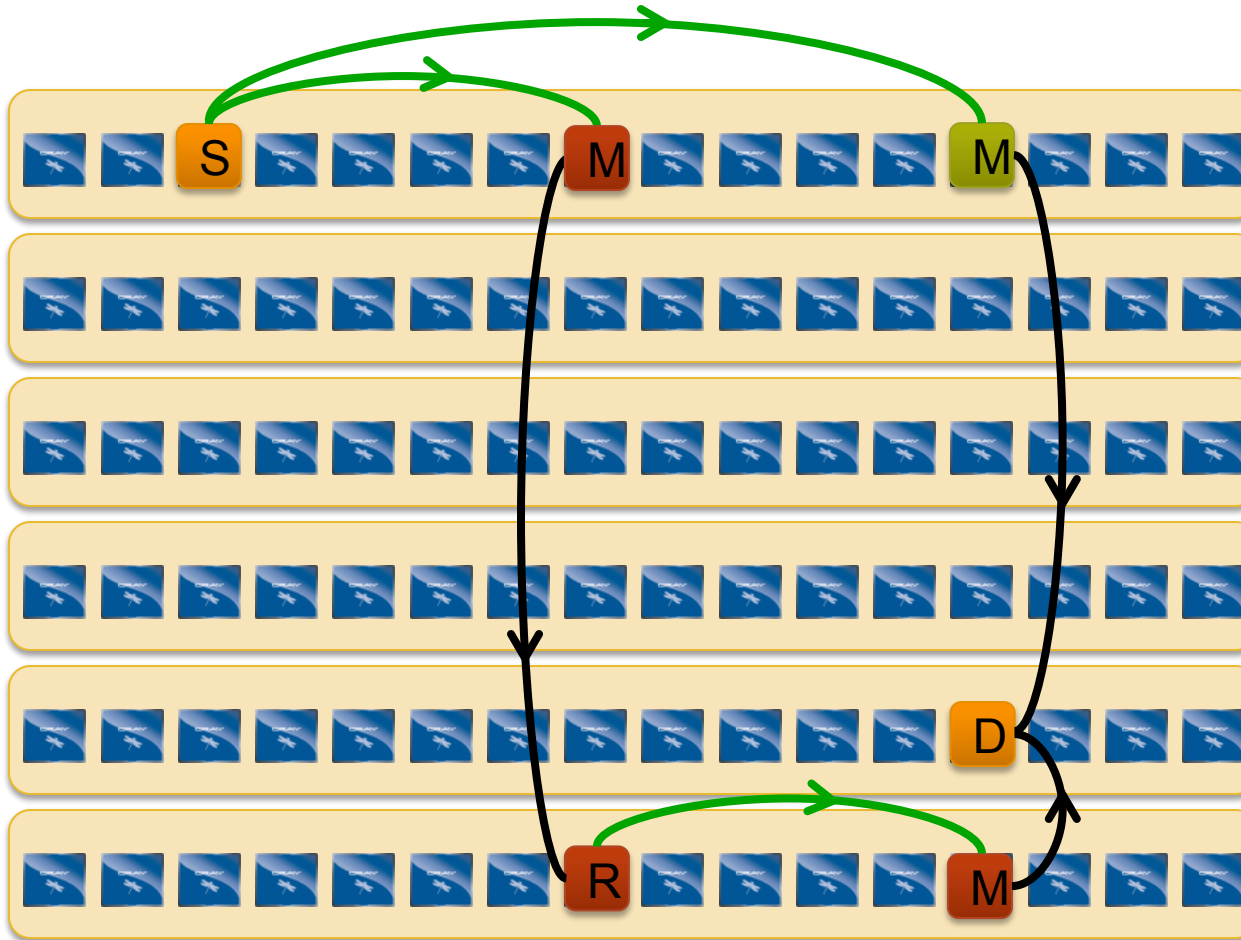
Cray XC30 Rank-2 Cabling



- Cray XC30 two-cabinet group
 - 768 Sockets
 - 96 Aries Chips



Cray XC30 Adaptive Routing



Minimal route between any two nodes in a group is just two hops

Non-minimal route requires up to four hops.

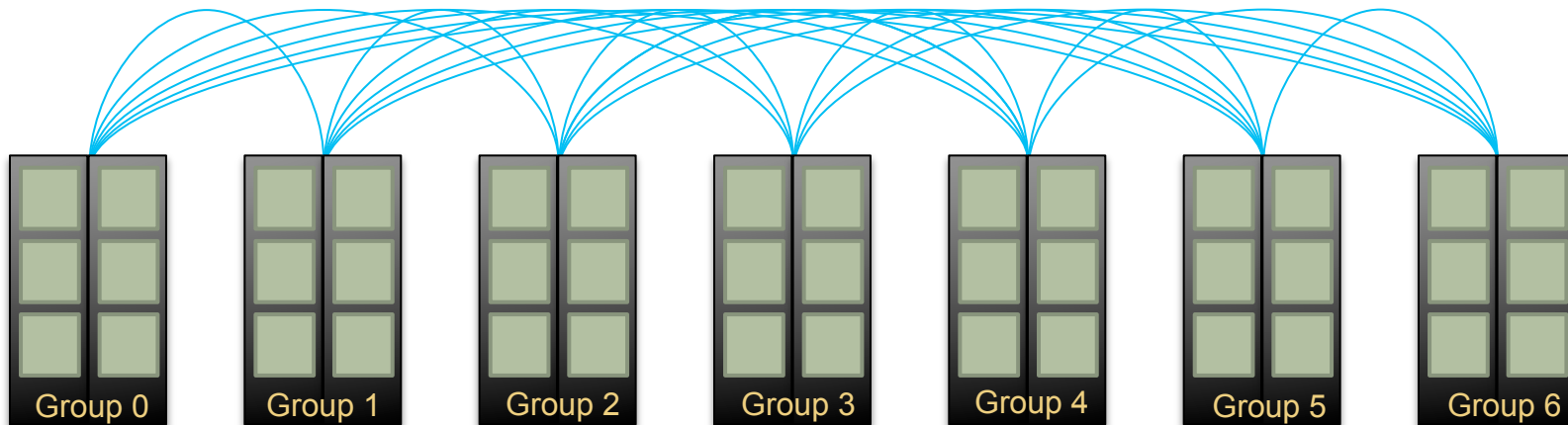
With adaptive routing we select between minimal and non-minimal paths based on load

The Cray XC30 Class-2 Group has sufficient bandwidth to support full injection rate for all 384 nodes with non-minimal routing

- **Adaptive routing allows the Cray XC network to handle a diverse set of traffic patterns at full speed**
 - Significant advantage over Infiniband on real traffic patterns

Cray XC30 – Rank-3 Network

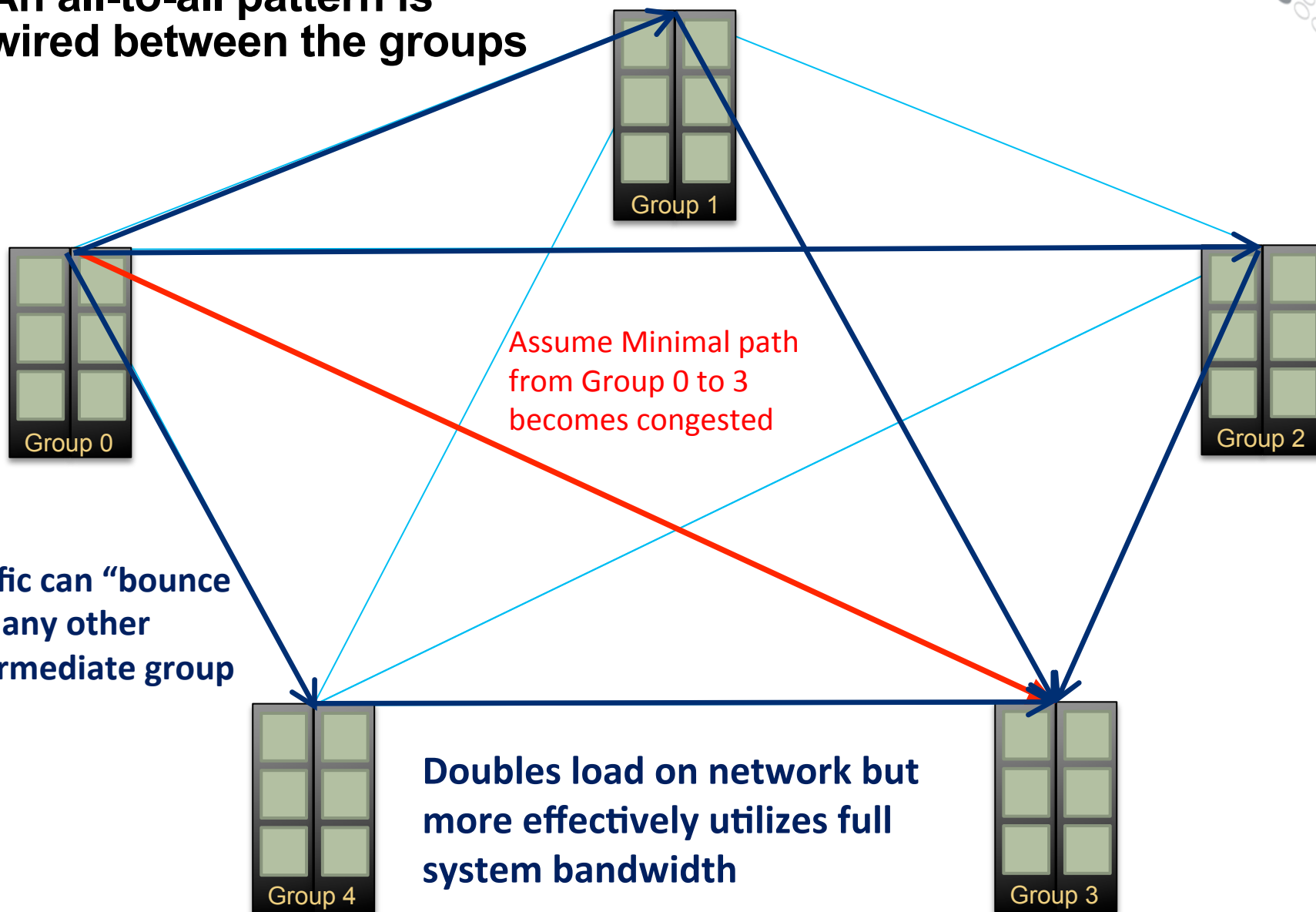
- An all-to-all pattern is wired between the groups using optical cables (blue network)
- The global bandwidth can be tuned by varying the number of optical cables in the group-to-group connections



Example: A 7-group system is interconnected with 21 optical “bundles”. The “bundles” can be configured between 2 or more cables wide, subject to the group limit.

Adaptive Routing over the Blue Network

- An all-to-all pattern is wired between the groups





Why use Huge Pages?

- **On edison huge pages are a performance enhancement**
 - On hopper hugepages were a functional requirement for some codes
- **The Aries may perform better with HUGE pages than with 4K pages.**
 - HUGE pages use less Aries resources than 4k pages
 - More important when remotely access large percentage of nodes memory in an irregular manner
 - Large AlltoAll
 - AMO GUPS
- **Still be watchful for memory page fragmentation**
 - Might still get “cannot run errors” because it cannot find enough large hugepages
- **Use modules to change default page sizes (man intro_hugepages):**
 - e.g. module load craype-hugepages#
 - craype-hugepages2M
 - craype-hugepages8M
 - craype-hugepages16M
 - craype-hugepages32M

MPI Latency and Bandwidth



Multipong Benchmarks

| Test Description | Measured | Units |
|---|----------|-------|
| Maximum Inter-Node Latency Single-Core, Farthest-node pair (1) | 1.920 | μsecs |
| Minimum Inter-Node Latency Single-Core, Nearest-node pair (2) | 1.498 | μsecs |
| Maximum Intra-Node Latency Single-Core, cross socket (3) | 0.545 | μsecs |
| Minimum Intra-Node Latency Single-Core, same socket (4) | 0.267 | μsecs |
| Maximum Inter-Node Latency Fully-packed Nodes, Farthest-node pair (5) | 2.452 | μsecs |
| Maximum Inter-Node Latency Fully-packed Nodes, Nearest-node pair (6) | 2.027 | μsecs |
| Maximum Bandwidth Multi-Core Nearest Nodes (7) | 9255 | MB/s |



Point-to-Point Aries vs. Gemini

| Typical Point-to-point bandwidth | | |
|----------------------------------|--------|--------|
| Case | Gemini | Aries |
| | (GB/s) | (GB/s) |
| “On Gemini/Aries” | ~5 | ~8-10 |
| “Long Range” | ~1.5-3 | ~8-10 |

- Long Range transfers on Aries will be able to adapt around any hot spots in the network and continue at full speed
- Maximum latency will be much lower on Aries

Optical network rarely limiting factor in real life



- **Most traffic patterns will be limited by the sustained injection bandwidth**
 - Sustained injection bandwidth is in the 3-6 Gbytes/sec range
 - Nearest Neighbor communication mostly stays on-group
- **Examples of optical bound benchmarks**
 - Full system alltoall with <50% of optical cables connected
 - Pure bi-section bandwidth tests, but that is not common in real codes
 - Global bandwidth intensive codes that are packed into just a few groups
 - Seems unlikely to occur in production
- **Less than full system runs are unlikely to be optical limited**
- **Communication intensive applications are more likely to be injection bandwidth bound rather than network bound**
 - Consider optimization that maximize on-node traffic and minimize off-node traffic

Additional Network test

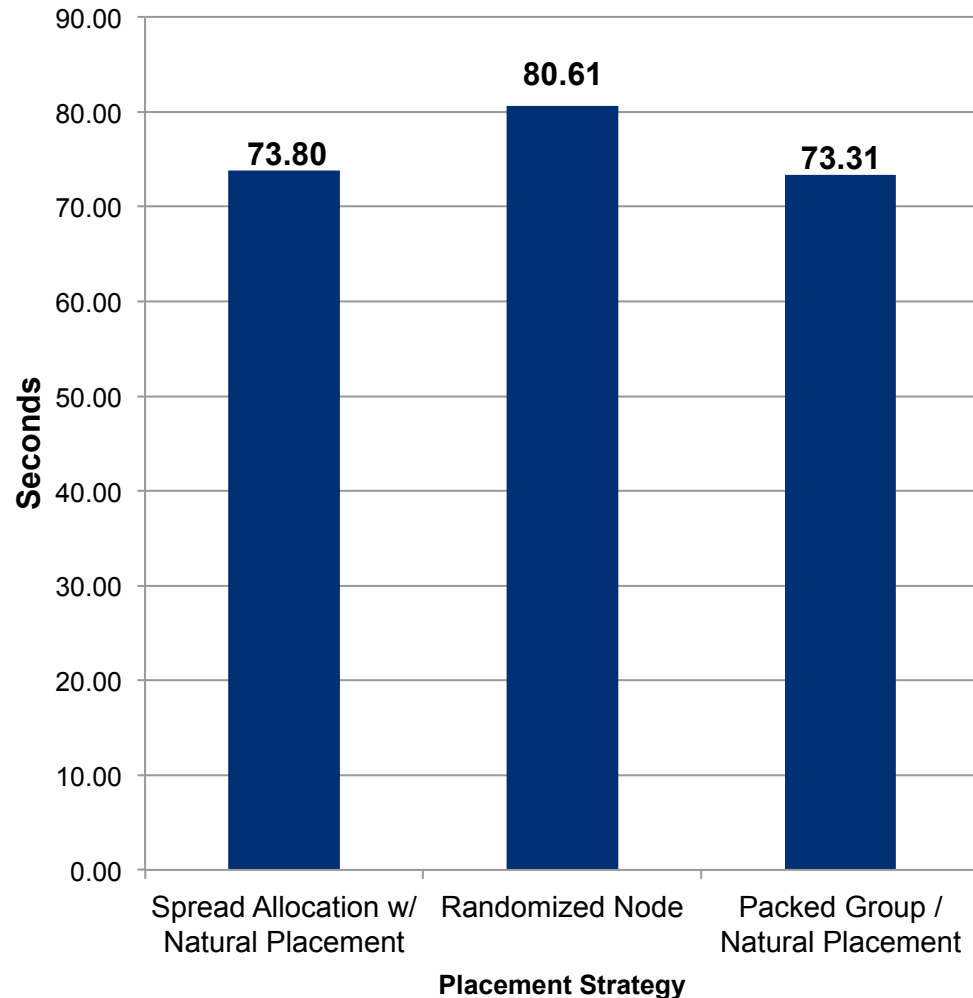
- **MPI_ALLTOALL**
 - Dmapp optimization during communication is available under 6.0
 - `MPICH_USE_DMAPP_COLL = 1`
 - Measured ~ 9 Tbytes / second of global bandwidth
 - Very good performance for this configuration
- **MPI Barrier / Allreduce – excellent scaling with dmapp version**
- **Initial conclusions:**
 - High speed network is healthy and performing well.
 - Full system performance is very good.
 - Adaptive routing working very well (as designed).

Placement Strategies impact on 3D stencil



- Run on 14 copies of a 3D stencil code simultaneously on a 28 cabinet system with partial optical network
- Spread Allocation w/ Natural Placement
 - Spread across the machine
 - “Naturally” fill your portion of the group before moving on to the next group
 - Preserves some spatial locality while still spreading out the job
- Randomized Node
 - Spread across the machine
 - No spatial locality
- “Packed Group” fills a cabinet before moving on to the next cabinet
 - Maximizes on-group traffic
- Conclusions
 - Natural placement a good idea
 - Don’t destroy spatial locality
 - Pack Group slightly better, but performance is not hurt significantly if job gets spread out

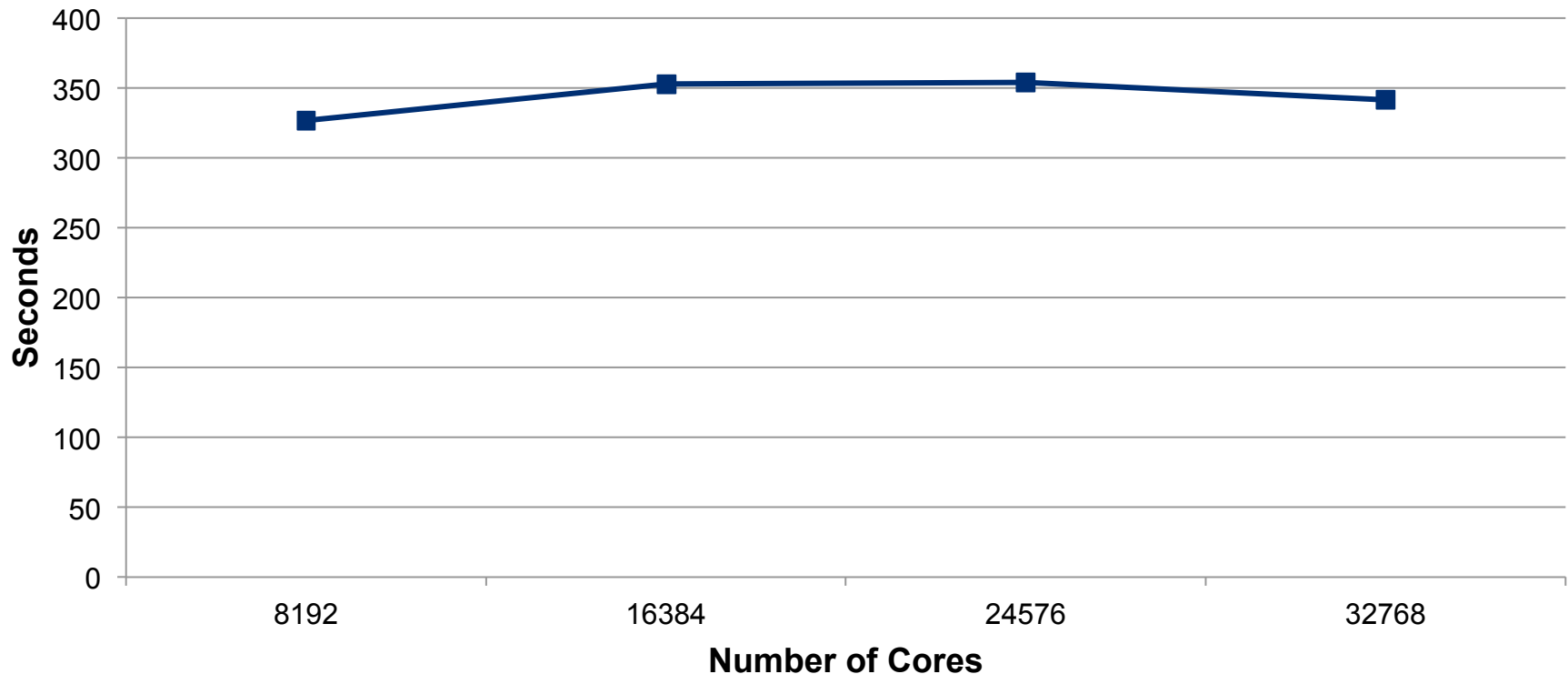
Walltime of 3D stencil code using different placement strategies



Near perfect scaling of MILC



MILC Weak Scaling Test on 12 cab with quarter optical network



- **MILC does a 4D Nearest Neighbor Halo exchange**
 - Cause significant network contention on a 3D torus
 - Significant amounts of traffic stays on group
 - Also sets up patterns where all off-group traffic goes to one other group
 - Would only work well if adaptive routing was working well



Summary

● On-node

- 24 cores per node on edison; similar to hopper
 - Edison has new –j1 vs –j2 (hyperthreading) feature
- Edison has ~2X the bandwidth of hopper per node
- Intel compiler now available

● Network

- Edison has improve injection bandwidth over hopper
- Edison has a greatly improved network bandwidth
 - Global bandwidth is significantly higher
 - Adaptive routing minimizes hot spots
 - Better scaling
 - Less job-job interference
- Communication intensive applications more likely to be injection bandwidth bound rather than network bound

● Overall application performance should be significantly improved compared to hopper

The End